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This shows that the problem has no solution. (c) The formulation is $\min x_1 x_2$.
s.t. $x_1 + x_2 = 2$ Since the constraint of this

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problem is linear, we eliminate x_2 from the objective and get an unconstrained problem, namely

$\min_{x_1} (2 - x_1) = (x_1 - 1)^2 + 1$. Obviously, when $|x_1 - 1| \gg 1$, we see that $(x_1 - 1)^2 + 1 \gg 1$.

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$p^T(B+I)^{-1}g+v$, (4.16) where v is a vector that satisfies $v^T(B+I)^{-1}g \geq 0$. (This condition ensures that v does not move back toward zero, but instead

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Solution continues to move roughly in the direction of $(B + \epsilon I)^{-1}g$. When B has zero eigenvalues but no negative eigenvalues, the Cauchy step p_C is used as the approximate solution of (4.9).

*Numerical Optimization - Amirkabir
University of Technology
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2= 1, and the optimal objective is 2. (b)

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The formulation is $\min x_1 + x_2$ (61a) s.t.

$$x_1^2 + x_2^2 = 3 \quad (61b)$$

(61c) Substituting equation (61c) into (61b), we get $x_1^2 + (3 - x_1)^2 = 3$ which implies $x_1^2 - 3x_1 + 4 = 0$. This inequality has no solution; thus the feasible region of the original problem is empty.

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